

Manual

Liquid Level Controller EKC 347



Application

The controller is used for regulation of the refrigerant level in:

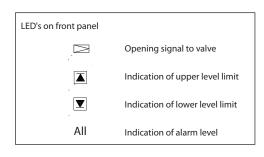
- Pump reservoirs
- Separators
- Intermediate coolers
- Economisers
- Condensers
- Receivers

System

A signal transmitter will constantly measure the refrigerant liquid level in the reservoir - the controller will receive the signal and subsequently control the valve, in order to control the refrigerant liquid level according to liquid level setpoint.

Functions

- · Liquid level control
- · Alarm if the set alarm limits are exceeded
- Relay outputs for upper and lower level limits and for alarm level
- Analog input signal which can displace the reference
- · PI control
- Low or High side control
- When AKV/A is selected, a MASTER/SLAVE system can run up to 3 AKV/A with distributed Opening Degree
- Manual control of output
- Limitation of Opening degree possible
- · ON/OFF operation with hysteresis



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Signaltransmitter With the capacitive rod it is possible to set the

refrigerant level within a wide range.

EKC 347

The controller receive a signal and are then able to contol low or high side applications. A analog input signal (voltage/ current) can displace the setpoint and then remote change of setpoint is thus possible.

EKC 347 does support 2 types of Danfoss expansion valves. (see below)

One analog input is available as feed back from

ICM in order to indicate Opening degreee of the

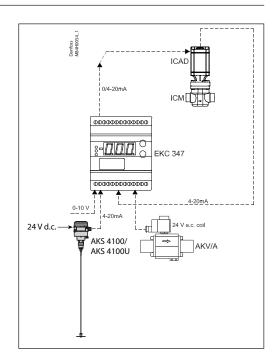
ICM.

Two types of Danfoss expansion valves can be Expansions valve

used

ICM - ICM are direct operated motorized valves driven by digital stepper motor type ICAD AKV/A - AKVA or AKV are pulse-width modulat-

ing expansion valves.

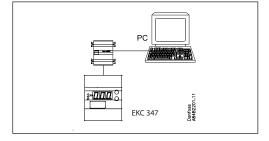


Extra options

PC operation

The controller can be provided with data communication, so that it may be hooked up with other products in the ADAP-KOOL® range of refrigeration controls. Operation, monitoring and data collection can then be performed from a PC

- either in situ or at a service company.

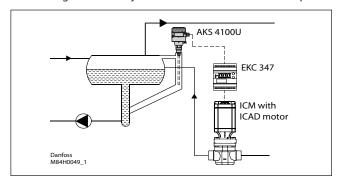




Application examples

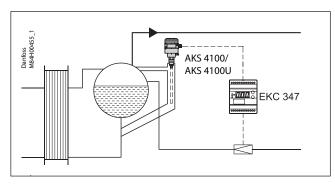
Pump reservoir

Modulating control of injection makes for a more stable liquid level and suction pressure.



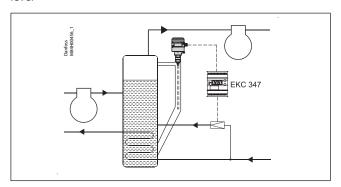
Separator on flooded evaporator

Modulating control and the valve's large capacity range ensure a stable level - even under conditions of quickly changing loads.



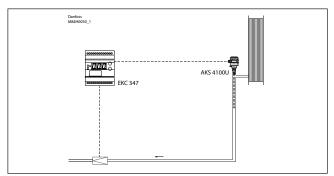
Intermediate cooler

The level transmitter's wide measuring range enables it to monitor the liquid at all levels of the reservoir - and hence to use the signal for safety functions in connection with the max. permissible level



Receiver / condenser

The control system's short reaction time makes it very suited for high-pressure float systems with small refrigerant charges.





Survey of functions

Function	Para- meter	Parameter by operation via data communication
Normal display		Level control
The liquid level is indicated in % The % value is calculated on the basis of the input signal and the definition in "o31".	-	Liquid level
The valve's actual opening degree can be displayed by giving the lower button a brief push (1s). Cf. also o17.	-	OD %
Reference		
Set point Regulation is based on the set value provided that there is no external contribution (o10). (Push both buttons simultaneously to set the setpoint).	-	SP Liquid Level
External contribution to the reference This setting determines how large a contribution is to be added to the set reference when the input signal is max (20 mA or 10 V. Cf. also o10). The value is set in %-points.	r06	r06 Ext. Ref.offset
Start/stop of regulation With this setting the level regulation can be started and stopped. Start/stop of level regulation can also be performed with the external contact function. Regulation is stopped if just one of them is OFF.	r12	r12 Main Switch
Alarm		Level Alarms
The controller can give alarm in different situations. When there is an alarm the three lowest LED's at the front of the controller will flash, and the alarm relay is cut in		
Limit for upper level Here you set the limit value for the upper level indication. The value is set in %. The relay for the upper level will become activated when the level exceeds the set value.	A01	A01 Upper Dev.
Limit for lower level Here you set the limit value for the lower level indication. The value is set in %. The relay for the lower level will become activated when the level drops below the set level.	A02	A02 Lower Dev.
Time delay for upper level limit When the limit value is exceeded a timer function will start. The relay will not become activated until the set time delay has been passed. The time delay is set in seconds.	A03	A03 Upper Delay
Delay for lower limit level When the limit value is exceeded a timer function will start. The relay will not become activated until the set time delay has been passed. The time delay is set in seconds.	A15	A15 Lower Delay
Limit for alarm level An alarm level can be set which when passed will activate the alarm relay- The value is set in %. Cf. also the definition in A18. If the limit alarm (A3) is not required, it can be avoided by means of the following setting in A16: 100: If the rising level definition has been chosen. (A18=0 or 2) 0: If the falling level definition has been chosen. (A18=1 or 3)	A16	A16 Limit Alarm
Time delay for alarm level When the alarm level is exceeded a timer function will start. The relay will not become activated until the set time delay has been passed. The time delay is set in seconds.	A17	A17 Limit Delay



Configuration of limit alarm (A3) level and lower limit alarm(A2) for pump cut-	A18	A18 Lim. LowMode
out. To define whether the limit alarm (A3) is linked to rising (A18=0) or falling level		
(A18=1).		
It is also possible to configurate the Relay for lower level limit when lower limit alarm (A2) is detected. Dedicated to switch off pumps at low level alarm.		
0: Rising level. When liquid level is higher than A16, and time in A17 has expired, A3 alarm is generated.		
1: Falling level . When liquid level is lower than A16, and time in A17 has expired, A3 alarm is generated. 2: Same function as if A18=0, but in addition (to that: - When liquid level is higher than A02. No A2 alarm and Relay for lower level limit,		
gives ON signal (cut in) on terminal 8 and 10. - When liquid level is lower than A02 and time in A15 has expired. A2 alarm is generated and Relay for lower level limit, gives OFF signal (cut out) on terminal 8 and 10. 3: Same function as if A18=1, but in addition (to that:		
- When liquid level is higher than A02. No A2 alarm and Relay for lower level limit, gives ON signal (cut in) on terminal 8 and 10.		
- When liquid level is lower than A02 and time in A15 has expired. A2 alarm is generated and Relay for lower level limit, gives OFF signal (cut out) on terminal 8 and 10.		
Function Alarm relay when A1, A2 or A3 alarms are detected. 0: Alarm relay to be activated when A1 or A2 or A3 are detected. 1: Alarm relay only to be activated when A3 is detected.	A19	A19 Alarm type (With setting = 0 the alarm is also transmitted via the data communica- tion)
Alarm relay The alarm relay will become activated if one of the set limits is exceeded or if the		With data communication the importance of the individual alarms can be
controller loses the input signal from the level-measuring unit.		defined. Setting is carried out in the "Alarm destinations" menu. See also page 11.
controller loses the input signal from the level-measuring unit. Control parameters		
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising.	n35	"Alarm destinations" menu. See also page 11.
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is	n35	"Alarm destinations" menu. See also page 11. Injection Settings
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Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is rising. High (1): Regulation on the high-pressure side. The valve opens when liquid level is	n35	"Alarm destinations" menu. See also page 11. Injection Settings
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is rising. High (1): Regulation on the high-pressure side. The valve opens when liquid level is rising. Period time An AKV/A valve is operated with pulses of a given length. The length depends on the opening degree required. If a large opening degree is required, the pulse will last for		"Alarm destinations" menu. See also page 11. Injection Settings n35 Low/High Pr.
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is rising. High (1): Regulation on the high-pressure side. The valve opens when liquid level is rising. Period time An AKV/A valve is operated with pulses of a given length. The length depends on the opening degree required. If a large opening degree is required, the pulse will last for an entire period time. A period time will thus comprise both open and closed valve. P - band If the value is reduced the regulating range will be reduced. (The P-band will be near the reference). I: Integration time Tn The I-link can be made passive by setting the value at max. (600s) (If the Tn value is increased the regulation becomes slower).	n13	"Alarm destinations" menu. See also page 11. Injection Settings n35 Low/High Pr. n13 AKV per.time
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is rising. High (1): Regulation on the high-pressure side. The valve opens when liquid level is rising. Period time An AKV/A valve is operated with pulses of a given length. The length depends on the opening degree required. If a large opening degree is required, the pulse will last for an entire period time. A period time will thus comprise both open and closed valve. P - band If the value is reduced the regulating range will be reduced. (The P-band will be near the reference). I: Integration time Tn The I-link can be made passive by setting the value at max. (600s) (If the Tn value is increased the regulation becomes slower). Neutralzone The function is only active if the selected expansion valve is of type ICM	n13	"Alarm destinations" menu. See also page 11. Injection Settings n35 Low/High Pr. n13 AKV per.time n04 P-band
Control parameters Definition of regulating principle Here you set whether the controller is to open or close the valve when the liquid level is rising. Low (0): Regulation on the low-pressure side. The valve closes when liquid level is rising. High (1): Regulation on the high-pressure side. The valve opens when liquid level is rising. Period time An AKV/A valve is operated with pulses of a given length. The length depends on the opening degree required. If a large opening degree is required, the pulse will last for an entire period time. A period time will thus comprise both open and closed valve. P - band If the value is reduced the regulating range will be reduced. (The P-band will be near the reference). I: Integration time Tn The I-link can be made passive by setting the value at max. (600s) (If the Tn value is increased the regulation becomes slower). Neutralzone	n13	"Alarm destinations" menu. See also page 11. Injection Settings n35 Low/High Pr. n13 AKV per.time n04 P-band n05 Tn sec.



Miscellaneous		Miscellaneous
Valve and output signal The controller can control three types of expansion valves - ICM or AKV/A. With AKV/A up to three EKC 347 controllers can be linked up to a MASTER/SLAVE function (this function is only used if there is a need for several parallel AKV/A expansion valves). The application is selected with one of the following settings: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 4-20 mA 4: AKV/A, AO: 0-20 mA or, if the master/slave function is used:: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:4-20 mA 7: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/2. AO:0-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 2/2. AO:0-20 mA 12: AKV/A, SLAVE 1/1. AO:0-20 mA - AO always updated 13: AKV/A, SLAVE 1/1. AO:0-20 mA- AO always updated	009	o09 AO type
14: AKV/A, SLAVE 1/2. AO:4-20 mA- AO always updated 15: AKV/A, SLAVE 1/2. AO:0-20 mA- AO always updated 16: AKV/A, SLAVE 2/2. AO:4-20 mA- AO always updated 17: AKV/A, SLAVE 2/2. AO:0-20 mA- AO always updated With settings 1 and 2 the AO [mA] signal is dedicated for the motor valve ICM. With settings 3, 4, AO [mA] will be send out a signal for process indications. With settings 6, 7, 8, 9, 10 or 11, AO [mA] on EKC 347 SLAVE, will be send out a signal for process indications. With settings 12, 13, 14, 15, 16 or 17, AO will also be updated (active) when DI is OFF		
Reference displacement If you wish to connect a signal that is to displace the controller's control reference, the signal must be defined in this menu. The signal is connected to terminals 19-21 or 20-21 0: No signal 1: 4 - 20 mA 2: 0 - 20 mA 3: 2 - 10 V 4: 0 - 10 V (The min. value will give no displacement. The max. value will displace the reference with the value set in menu r06).	o10	o10 Al type
Input signal from the level-measuring unit The input signal for terminals 14-16 or 15-16 must be defined: 0: No signal 1: Current signal of 4-20 mA 2: Voltage signal. The voltage range must be set in the next two menus. (If the connections are a master/slave system and the signal to the master is 4 to 20 mA, the setting in the slave modules must also be selected to 1 – this must be done, even if the signal is connected to the voltage input).	o31	o31 Levelsign.
Voltage signal's lower value (only if the setting in 031 = 2).	o32	o32 Lev. V. Low
Voltage signal's upper value (only if the setting in o31 = 2)	o33	o33 Lev. V. High
Position signal If a ICM valve is selected it is possible to have ICM valve position as a [mA] feed back signal 0: Not used 1: ICM mA feedback signal from connected ICAD. 2: Not used	o34	o34 Valve feedb.
Frequency Set the net frequency.	o12	o12 50 / 60 Hz (50=0, 60=1)
Address If the controller is built into a network with data communication, it must have an address, and the master gateway of the data communication must then know this address. These settings can only be made when a data communication module has been mounted in the controller and the installation of the data communication cable has been completed. This installation is mentioned in a separate document "RC8AC"		Following installation of a data communication module, the controller can be operated on a par with the other controllers in ADAP-KOOL® refrigeration controls.
The address is set between 1 and 60	o03	-
The address is sent to the gateway when the menu is set in pos. ON (The setting will automatically change back to Off after a few seconds.)	o04	-



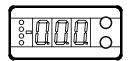
Language This setting is only required when data communication is connected to the controller. Settings: 0=English, 1=German, 2=French, 3=Danish, 4=Spanish, 5=Italian, and 6=	o11	o11 Language
Swedish When the controller is operated via data communication, the texts in the right-hand column will be shown in the selected language.		
When you change the setting to an other language you must activate o04 before "the new language" can be visible from the AKM program.		
Selection of parameter for displays and AO The selection depends on the setting made in menu "o34". The selected value to display is also send to AO, except when ICM or AKV/A as MASTER, has been selected as valve type (o09=1 or 2 or 5)	o17	o17 Display / AO
If o34 has been set at 0, the subsequent setting of o17 will mean: 0: The liquid level will be shown in the "normal display" 1: The valve's opening degree OD will be shown in the "normal display"		
If o34 has been set at 1, the subsequent setting of o17 will mean: 0: The liquid level will be shown in the "normal display" 1: The ICM valve position feed back signal [%] will be shown in the "normal display"		
The normal display has now been selected. If the other is requested, activate the controllers lowest button This will give a display showing of liquid level/opening degree - or vice versa. After five seconds the display will revert to the original mode.		
Manual control of outputs In connection wit service the individual relay outputs and the AKV/A output can be put in pos. ON. But not until regulation has been stopped. OFF: No override 1: Relay for upper level is ON 2: Relay for lower level is ON	o18	-
3: AKV/A output is ON 4: Alarm relay is activated (terminals 12 and 13 will be connected)		
Service		Service
A number of controller values can be printed for use in a service situation		
Read liquid level	u01	u01 Liquid level
·		•
Read the control reference (Set reference + any contribution from external signal)	u02	u02 Liq. Lev Ref
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree	u02 u24	u02 Liq. Lev Ref u24 OD %
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21	u02	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received	u02 u24	u02 Liq. Lev Ref u24 OD %
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received	u02 u24 u06	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16	u02 u24 u06 u07	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16	u02 u24 u06 u07	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals	u02 u24 u06 u07 u30 u31	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5)	u02 u24 u06 u07 u30 u31 u32	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree	u02 u24 u06 u07 u30 u31 u32 u33	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb %
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5)	u02 u24 u06 u07 u30 u31 u32 u33 u08	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5)	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5) Read status of input DI (start/stop input)	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay ON is operating status with alarm DO2 Upper alarm Read status of the relay for the upper
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5) Read status of input DI (start/stop input)	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay ON is operating status with alarm DO2 Upper alarm Read status of the relay for the upper level limit DO3 Lower alarm Read status of the relay for the lower level limit
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5) Read status of input DI (start/stop input) Operating status Operating status of the controller can be called forth in the display. Push briefly (1s) the upper button. If there is a status code, it will be shown on the display. (Status codes have lower priority than alarm codes. In other words, you cannot see a status code, if there is an active alarm).	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay ON is operating status with alarm DO2 Upper alarm Read status of the relay for the upper level limit DO3 Lower alarm Read status of the relay for the lower
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5) Read status of input DI (start/stop input) Operating status Operating status of the controller can be called forth in the display. Push briefly (1s) the upper button. If there is a status code, it will be shown on the display. (Status codes have lower priority than alarm codes. In other words, you cannot see a status code, if there is an active alarm). The individual status codes have the following meanings:	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay ON is operating status with alarm DO2 Upper alarm Read status of the relay for the upper level limit DO3 Lower alarm Read status of the relay for the lower level limit EKC State (0 = regulation)
Read the control reference (Set reference + any contribution from external signal) Read valve's opening degree Read value of the external current signal (reference displacement) which is received on terminals 19-21 Read value of the external voltage signal (reference displacement) which is received on terminals 20-21 Read value of the current signal (level signal) received on terminals 15-16 Read value of the voltage signal (level signal) received on terminals 14-16 Read value of the current signal (position signal from the valve) received on terminals 17-18 Read position signal from the valve. The value is converted into % of the total opening degree Read value of the delivered current signal (terminals 2-5) Read status of input DI (start/stop input) Operating status Operating status of the controller can be called forth in the display. Push briefly (1s) the upper button. If there is a status code, it will be shown on the display. (Status codes have lower priority than alarm codes. In other words, you cannot see a status code, if there is an active alarm).	u02 u24 u06 u07 u30 u31 u32 u33 u08 u10	u02 Liq. Lev Ref u24 OD % u06 Ext. Ref. mA u07 Ext. Ref. V u30 Levelsign. mA u31 Levelsign. V u32 Valve fb mA u33 Valve fb % u08 AO mA u10 DI DO1 Limit alarm Read status of alarm relay ON is operating status with alarm DO2 Upper alarm Read status of the relay for the upper level limit DO3 Lower alarm Read status of the relay for the lower level limit EKC State



Operation

Display

The values will be shown with three digits, and after an operation the controller will return to its standard mode and show the measured liquid level.



Light-emitting diodes (LED) on front panel
There are LED's on the front panel which will light
up when the corresponding relay is activated.
The upper LED will indicate the valve's opening
degree. A short pulse indicates a slow liquid flow
and a long pulse a fast liquid flow.

The three lowest LED's will flash, if there is an error in the regulation.

In this situation you can upload the error code on the display and cancel the alarm by giving the uppermost button a brief push.

The buttons

When you want to change a setting, the two buttons will give you a higher or lower value depending on the button you are pushing. But before you change the value, you must have access to the menu. You obtain this by pushing the upper button for a couple of seconds - you will then enter the column with parameter codes. Find the parameter code you want to change and push the two buttons simultaneously. When you have changed the value, save the new value by once more pushing the two buttons simultaneously.

• •

Gives access to the menu (or cutout an alarm)



Gives access to changes

Saves a change

Examples of operations

Set reference

- 1. Push the two buttons simultaneously
- 2. Push one of the buttons and select the new value
- 3. Push both buttons again to conclude the setting

Set one of the other menus

- Push the upper button until a parameter is shown
- Push one of the buttons and find the parameter you want to change
- 3. Push both buttons simultaneously until the parameter value is shown
- 4. Push one of the buttons and select the new value
- 5. Push both buttons again to conclude the setting



Menu survey SW = 1.1x

Function	Parameter	Min.	Max.	Fac. setting
				3
Normal display Read the measured liquid level		%		50.0
nead the measured liquid level	-	90		50.0
If you wish to see the actual opening degree, give the lower button a brief push	-	%		0
If you wish to set the required setpoint you obtain access by pushing both buttons simultaneously	-	0%	100%	100
Level control		,		
External contribution to the reference. Cf. also o10.	r06	-100	100	0.0
Value is set in %-points.	10	055.00	011/4	
Start / stop of level control	r12	OFF/0	ON/1	1
Alarm Upper level limit	A01	0 %	100%	85
Lower level limit	A01	0%	100%	15
Time delay for upper level limit	A02	0% 0 s	999 s	50
Time delay for lower level limit	A15	0 s	999 s	10
Level alarm limit	A16	0 %	100 %	20
Delay for level alarm	A17	0 s	999 s	0
The level alarm is linked to:	7.17		3333	
0: Rising level (higher level than A16)				
1: Falling level (lower level than A16)				
2: Same function as if A18=0. When A2 alarm is generated and Relay for lower level limit, gives OFF	A18	0	3	0
signal (cut out).				
3: Same function as if A18=1 When A2 alarm is generated and Relay for lower level limit, gives OFF signal (cut out).				
signal (cut out).				
Function for Alarm relay when A1, A2 or A3 alarms are detected.				
0: Alarm relay to be activated when A1 or A2 or A3 are detected.	A19	0	1	0
1: Alarm relay only to be activated when A3 is detected.				
Regulating parameters				
P - band	n04	0%/Off	200%	30
I: Integration time Tn	n05	60	600/Off	400
Period time (only if AKV/A valve is used)	n13	3 s	10 s	6
Max. opening degree		0%		
	n32	+	100%	100
Min. opening degree	n33	0%	100%	0
		+		+
Min. opening degree Neutral zone (only for ICM valve)	n33	0%	100%	0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle	n33 n34	0% 2%	100%	0 2
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising)	n33	0%	100%	0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle	n33 n34	0% 2%	100%	0 2
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising)	n33 n34	0% 2%	100%	0 2
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising)	n33 n34	0% 2%	100%	0 2
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 4-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA Or if a master/slave function is used:	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 4-20 mA 4: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:4-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 4-20 mA 3: AKV/A, AO: 4-20 mA 4: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, SLAVE 1/1. AO:4-20 mA 7: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/2. AO:4-20 mA 9: AKV/A, SLAVE 1/2. AO:0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 4-20 mA 4: AKV/A, AO: 4-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:0-20 mA 7: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/2. AO:4-20 mA 9: AKV/A, SLAVE 1/2. AO:4-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:0-20 mA 7: AKV/A, SLAVE 1/1. AO:0-20 mA 9: AKV/A, SLAVE 1/2. AO:0-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 2/2. AO:0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA 4: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, SLAVE 1/1. AO:4-20 mA 8: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/1. AO:0-20 mA 9: AKV/A, SLAVE 1/2. AO:0-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 2/2. AO:0-20 mA 12: AKV/A, SLAVE 2/2. AO:0-20 mA	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA 3: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/1. AO:0-20 mA 9: AKV/A, SLAVE 1/2. AO:0-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 2/2. AO:4-20 mA 12: AKV/A, SLAVE 1/1. AO:4-20 mA - AO always updated 13: AKV/A, SLAVE 1/1. AO:0-20 mA-AO always updated	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 4-20 mA 4: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:4-20 mA 7: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/2. AO:4-20 mA 9: AKV/A, SLAVE 1/2. AO:4-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 1/1. AO:0-20 mA 12: AKV/A, SLAVE 1/1. AO:0-20 mA - AO always updated 13: AKV/A, SLAVE 1/1. AO:0-20 mA- AO always updated 14: AKV/A, SLAVE 1/2. AO:4-20 mA- AO always updated	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0
Min. opening degree Neutral zone (only for ICM valve) Definition of regulating principle Low: On the low-pressure side (valve closes when liquid level is rising) High: On the high-pressure side (valve opens when liquid level is rising) Miscellaneous Controller's address ON/OFF switch (service-pin message) Define valve and output signal: 1: ICM. AO: 4-20 mA 2: ICM. AO: 0-20 mA 3: AKV/A, AO: 0-20 mA 3: AKV/A, AO: 0-20 mA Or if a master/slave function is used: 5: AKV/A, MASTER 6: AKV/A, SLAVE 1/1. AO:0-20 mA 8: AKV/A, SLAVE 1/1. AO:0-20 mA 9: AKV/A, SLAVE 1/2. AO:0-20 mA 10: AKV/A, SLAVE 1/2. AO:0-20 mA 11: AKV/A, SLAVE 2/2. AO:4-20 mA 12: AKV/A, SLAVE 1/1. AO:4-20 mA - AO always updated 13: AKV/A, SLAVE 1/1. AO:0-20 mA-AO always updated	n33 n34 n35	0% 2% Low/0	100% 25% Hig/1 60 ON	0 2 0

 $^{^{*}}$) This setting will only be possible if a data communication module has been installed in the controller.

Factory setting
If you need to return to the factory-set values, it can be done in this way:
- Cut out the supply voltage to the controller
- Keep both buttons depressed at the same time as you reconnect the supply voltage



Continued from previous page

Continued from previous page				
Define the input signal on terminals 10, 20, 21 (external reference displacement)	o10	0	4	0
0: OFF				
1: 4-20 mA				
2: 0-20 mA				
3: 2-10 V				
4: 0-10 V				
Language	o11*	0	6	0
0=English, 1=German, 2=Frensh, 3=Danish, 4=Spanish, 5=Italian, 6=Swedish. When you change the	.			
setting you must also activate o04.				
Set supply voltage frequency	012	0/50 Hz	1/60 Hz	0
Selection of parameter for display and AO (except from when o09=1,2 or 5)	017	0,30112	1	0
If 634 = 0:	017	ľ	'	l ^o
0: Liquid level is show				
1: Valve's opening degree OD will be shown				
If o34 = 1:				
0: Liquid level is show				
1: The ICM valve position feed back signal [%] will be shown				
Manual control of outputs:	o18	OFF	4	0
OFF: No manual control				
1: Upper level relay put in pos. ON				
2: Lower level relay put in pos. ON				
3: AKV/A output put in pos. ON				
4: Alarm relay activated (cut out)				
Define input signal (level signal) on terminals 14, 15, 16	o31	0	2	1
0: OFF				
1: 4-20 mA				
2: 0-10 V (also set the voltage values in the next two menus)				
Read functional description if the connection used is a master/slave function.				
Define input signal's lower value for terminal 14, if required	o32	0.0 V	4.9 V	4.0
Define input signal's upper value for terminal 14, if required	o33	5.0 V	10 V	6.0
Define input signal on terminals 17-18	o34	0	2	0
0: Not used				
1: ICM mA feedback signal from ICAD connected				
2: Not used				
Service				
Read liquid level	u01			9/
Read liquid level reference	u02			9/
Read external contribution to the reference	u06			m/
Read external contribution to the reference Read current signal on the analog output	u07 u08			\ \
Read status of input DI	u10			m _F
Read valve's opening degree	u24			9/
Read level signal	u30			m/
Read level signal	u31			\
Read signal from ICM/ICAD	u32			m <i>l</i>
Read signal from ICM/ICAD converted into %	u33			9/

^{*)} This setting will only be possible if a data communication module has been installed in the controller.

Factory setting
If you need to return to the factory-set values, it can be done in this way:

- Cut out the supply voltage to the controller

 Keep both buttons depressed at the same time as you reconnect the supply voltage

Error messages

The controller can give the following messages:			
E1		Errors in the controller	
E12	Error message	The external reference contribution is outside the range	
E21		Level signal outside the range 1)	
E22		Signal from ICM/ICAD outside the range	
A1		Upper level limit reached	
A2	Alarm message	Lower level limit reached	
A3		Alarm level limit reached	

1) If E21 is detected. EKC 347 will force the valve to close or open the valve depending af n35 $\,$

If Low pressure has been selected. (n35=0)

The valve is forced to fully closed, however if Min. Opening Degree (n33) is higher than 0 the valve will open to the value of n33

If High pressure has been selected. (n35=1)

The valve is forced to fully open, however if Max. Opening Degree (n32) is lower than 100 the valve will open to the value of n32



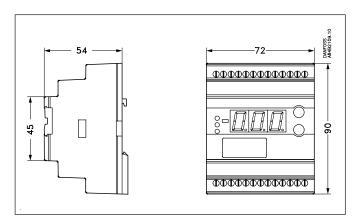
Ordering

Туре	Function	Code No.
EKC 347	Liquid level controller	084B7067
EKA 174	Data communication module (accessories), (RS 485 module) with galvanic separation	084B7124

Level transmitter/controller:Kindly refer to catalogue RK0YG AKV / AKVA Valves:Kindly refer to catalogue RK0YG ICM and ICAD.....Kindly refer to DKRCI.PD.HT0.A

Data

	24 V a.c. +/-15% 50/60 Hz, 60 VA			
Supply voltage	(the supply voltage is galvanically separated from the input and output signals. Input/output are not individual galvanic isolated)			
Power consumption	Controller 20 W coil for AKV	5 VA 55 VA		
	Level signal *	4-20 mA or 0-10 V		
Input signal * Ri =	Reference displacement *	4-20 mA, 0-20 mA, 2-10 V or 0-10 V		
0(4)-20mA:100 ohm 0(2)-10 V: 100 kohm	ICM valve feedback signal *	From ICAD 0/4-20 mA		
(2) 10 11 100 NO	Contact function start/stop of regulation			
Relay output	2 pcs. SPST	AC-1: 4 A (ohmic)		
Alarm relay	1 pcs. SPST	AC-15: 3 A (inductive)		
Current output	0-20 mA or 4-20 mA Max. load: 500 ohm			
Valve connection	ICM - via current output AKV/A- via 24 a.c. Pulse-Width Modulatin	g output		
Data communication	Possible to connect a data communication module			
Forder	-10 - 55°C, during operation -40 - 70°C, during transport			
Environments	20 - 80% Rh, not condensed			
	No shock influence / vibrations			
Enclosure	IP 20			
Weight	300 g			
Mounting	DIN rail			
Display	LED, 3-digits			
Terminals	max. 2.5 mm² multicore			
Approvals	EU Low Voltage Directive and EMC demands re CE-marking complied with. LVD-tested acc. to EN 60730-1 and EN 60730-2-9 EMC-tested acc. to EN61000-6-3 and EN 61000-6-2			





Connections

Necessary connections Terminals: Supply voltage 24 V a.c. 25-26 15-16 Signal from level transmitter type AKS 4100/4100U or Signal from transmitter 0-10 V 14-16 23-24 Expansion valve type AKV or AKVA or Expansion valve type: ICM with ICAD 2-5 1-2 Switch function for start/stop of regulation. If a switch is not connected, terminals 1 and 2 must be shortcircuited.

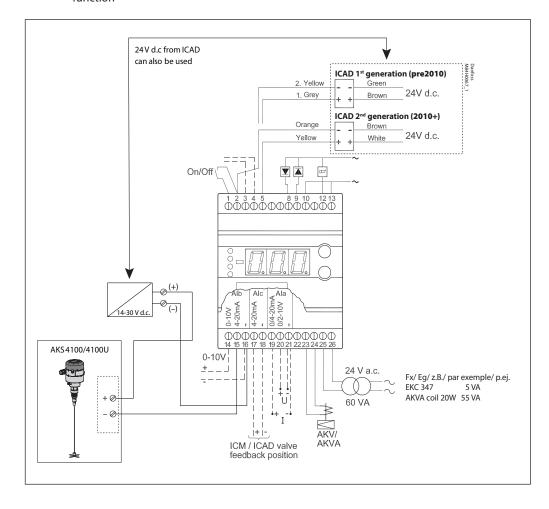
Application dependent connections

Terminal:

12-13 Alarm relay. See A19 and A18
8-10 Relay for lower level limit. See A18 for setting of ON (cut in) or OFF (cut out) function

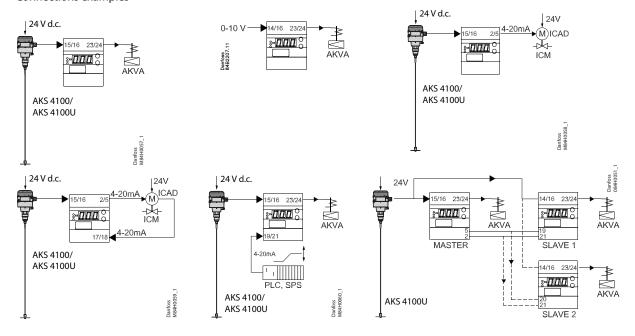
9-10	Relay for upper level limit. There is
	connection between 9 and 10 when
	the set value is passed
17-18	ICM valve feedback signal from ICAD
	0/4-20 mA
19-21	Current signal <u>or</u>
20-21	Voltage signal from other regulation
	(for external reference displacement)
3-4	Data communication
	Mount only, if a data communication
	module has been mounted.

It is <u>important</u> that the installation of the data communication cable be done correctly. Cf. separate literature No. RC8AC...

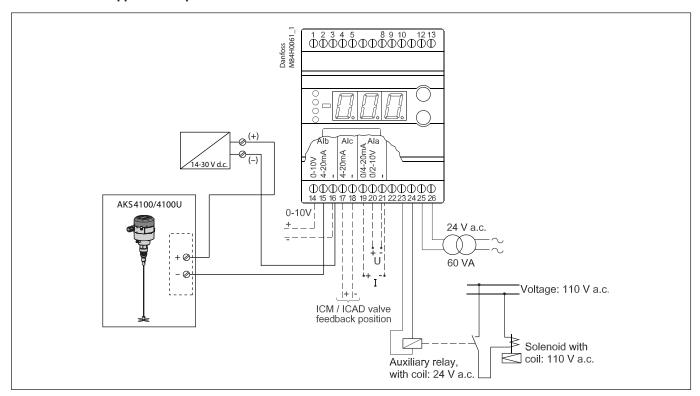




Connections examples

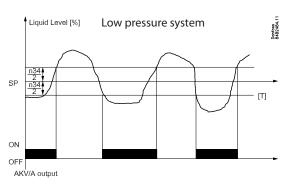


EKC 347 - ON/OFF Application. Open/Close solenoid valve with coil 110 V



ON/OFF application Beside of modulating PI control EKC 347 does also support ON/OFF operation with hysteresis.

To ensure this operation:
P.Band must be (n04)=0%//OFF
Hysteresis is given by (n34)
Setpoint as normal procedure. (pushing the upper/lower buttons simultaneously)
Low or High side system. (n35)









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